$$\frac{1.2.4}{G} Conserved quantities and statistical independence
of maccoscopic volumes
See Canden & hipschips, Statistical Rechanics
lionville's equation Consider a classical system comparising N
particles whose position and macenta are denoted as
 $\vec{q}_i^2 = \begin{pmatrix} q_{i,x} \\ q_{i,y} \\ h_{i,y} \end{pmatrix} \qquad h \quad \vec{p}_i^2 = \begin{pmatrix} p_{i,y} \\ h_{i,y} \\ h_{i,y} \end{pmatrix}$   
We write the dynamis as  
 $\vec{q}_i^2 = \frac{\partial H}{\partial \vec{p}_i^2} \qquad h \quad \vec{p}_i^2 = -\frac{\partial H}{\partial \vec{q}_i^2} \qquad when \quad \frac{\partial}{\partial \vec{q}_i^2} = \begin{pmatrix} \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q}_i} \end{pmatrix}$   
 $\vec{R} = \frac{\partial H}{\partial \vec{p}_i^2} \qquad h \quad \vec{p}_i^2 = -\frac{\partial H}{\partial \vec{q}_i^2} \qquad when \quad \frac{\partial}{\partial \vec{q}_i^2} = \begin{pmatrix} \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q}_i} \end{pmatrix}$   
 $\vec{R} = \frac{\partial}{\partial \vec{p}_i^2} \qquad d \quad \vec{p}_i^2 = -\frac{\partial}{\partial \vec{q}_i^2} \qquad when \quad \frac{\partial}{\partial \vec{q}_i^2} = \begin{pmatrix} \frac{\partial}{\partial \vec{q}_i} \\ \frac{\partial}{\partial \vec{q$$$

can define a probability ament  $\tilde{J}(\tilde{z}\tilde{q}\tilde{c},\tilde{p}\tilde{c}^{2},t) = g(\tilde{z}\tilde{q}\tilde{c},\tilde{h}\tilde{c}^{2},t) \begin{pmatrix} \tilde{y}_{1}\\ \tilde{y}_{2}\\ \tilde{y}_{1}\\ \tilde{y}$ 

$$\frac{\partial}{\partial t} g(\vec{q}_{i},\vec{p}_{i},\epsilon) = -\frac{\partial}{\partial t_{i}} \frac{\partial}{\partial t_{i}} \left[ \dot{q}_{i},\vec{p}_{i},\epsilon \right]$$

$$= -\frac{\sum_{i=r}}{\sum_{i=r}} \frac{\sum_{\alpha=r,\alpha,\beta}}{\partial \vec{q}_{i}} \left[ \dot{q}_{i},\beta(\vec{t}_{i},\vec{h}_{i},\epsilon) \right] + \frac{\partial}{\partial t_{i}} \left[ \dot{h}_{i,\alpha}\beta(\vec{t}_{i},\vec{h}_{i},\epsilon) \right]$$

$$= -\frac{\sum_{i=r}}{\sum_{i=r}} \frac{\partial}{\partial \vec{q}_{i}} \cdot \left[ \vec{q}_{i},\beta \right] + \frac{\partial}{\partial t_{i}} \cdot \left[ \vec{p}_{i},\beta \right]$$

$$= -\frac{\sum_{i=r}}{\sum_{i=r}} \frac{\partial}{\partial \vec{q}_{i}} \cdot \left[ \vec{q}_{i},\beta \right] + \frac{\partial}{\partial t_{i}} \cdot \left[ \vec{p}_{i},\beta \right]$$

$$= -\frac{\sum_{i=r}}{\sum_{i=r}} \frac{\partial}{\partial \vec{q}_{i}} \cdot \frac{\partial}{\partial t_{i}} - \frac{\partial}{\partial t_{i}} \cdot \frac{\partial}{\partial \vec{p}_{i}} = -\sum_{i=r} \frac{\partial}{\partial t_{i}} \cdot \frac{\partial}{\partial t_{i}}$$
where we have introduced the Poisson BRACKET
$$\left\{ A, B \right\} = \sum_{i=r}^{\infty} \sum_{\alpha=r,\alpha,\beta} \frac{\partial}{\partial t_{i,\alpha}} \frac{\partial}{\partial t_{i,\alpha}} - \frac{\partial}{\partial t_{i,\alpha}} - \frac{\partial}{\partial t_{i,\alpha}} \frac{\partial}{\partial t_{i,\alpha$$

$$\frac{\ln g \text{ is ``additive''} }{\operatorname{s Two subsystems}} S_{i} = \left\{ \tilde{q}_{i'}^{*}, \tilde{p}_{i'}^{*} \right\} \& S_{2} = \left\{ \tilde{q}_{2}^{*}, \tilde{p}_{2}^{*} \right\}$$

$$\frac{\ln g \text{ is ``additive''} }{\operatorname{stronge}} and Huus assumed unconclusted:$$

$$S_{i}\left( \left\{ \tilde{q}_{i'}^{*}, \tilde{q}_{2}^{*}, \tilde{p}_{2}^{*} \right\} \right) \cong S_{i}\left( \left\{ \tilde{q}_{i'}^{*}, \tilde{p}_{i'}^{*} \right\} \right) S_{2}\left( \left\{ \tilde{q}_{2}^{*}, \tilde{p}_{2}^{*} \right\} \right)$$

$$= \operatorname{s Lu} S_{iu2} = \operatorname{lus}_{i} + \operatorname{lus}_{2}$$

This is a second appealing justification of the Boltzmann weight. Still not a derivation = KINETIC THEORY OF GASES.

Goal: Start from some initial condition & characterize the evolution of the system. t=0<sup>+</sup> t = ~~ t=0<sup>-</sup> First challenge: The joint know ledge of all q'e d'p? is clearly too much information = identify the night level of descriptions, c.e. the good course grained observables and build their dynamics (e.g. density field). 2.1) From the liouville equation to the BBGKY hierarchy 2.1.1) The Gonville equation  $\partial_{z}g = -\left\{g,H\right\} = -\frac{\lambda}{2} \frac{\partial_{z}}{\partial \overline{q_{i}}} - \frac{\partial_{t}}{\partial \overline{q$  $= -\frac{\sum_{i=1}^{n} \left( \frac{\partial S}{\partial q_{i}^{2}} \cdot \frac{\overline{p_{i}^{2}}}{m} - \frac{\partial S}{\partial \overline{p_{i}^{2}}} \cdot \frac{\partial U}{\partial \overline{q_{i}^{2}}} - \frac{\partial S}{\partial \overline{p_{i}^{2}}} \cdot \frac{\partial V(q_{i}^{2} - \overline{q_{j}^{2}})}{\partial \overline{q_{i}^{2}}} \right]$ - { 3, H, 3 = frue evolution of g due to evolution of gwhen V=0intuactions Allin all

 $\partial_{\xi} g + \{g, H_i\} = \sum_{i=i}^{N} \left[ \frac{\partial g}{\partial \overline{p_i}} \cdot \sum_{j \neq i} \frac{\partial V(\overline{q_i}, \overline{q_j})}{\partial \overline{q_i}} \right]$ 



2.1.2) Coarse-grained description The joint probability distribution g( [92, P23, t) contains way too much information = intro Luce coarse-grained observablisto Les cuiter the macroscopic evolution of the system = Q: How? Which observable should we use o <u>General idea:</u> We need to identify the fields that allow us to derive a closed, self constant des cription of the system at large scales = Verg difficult tash in general Exaples <u>Micro:</u> a bunch of particles <u>Hano:</u> the diffusion equation doing random walks  $\xrightarrow{-0}$   $\frac{Hano:}{2} g(\bar{n}, \epsilon) = OO g(\bar{n}, \epsilon)$  $\partial_{\epsilon} g(\bar{a},\epsilon) = 0 \land g(\bar{a},\epsilon)$